XSTEP Absolute **AZ**

0.36°/Geared *Xster* AR

0.72°/Geared **RKI**

DC Input Motor & Driver 0.36°/Geared Absolute AZ 0.36°/Geared Q/STEP AR

> 1.8°/0.72° /0.36° CVK 0.72°/0.36° /Geared CRK

1.8°/Geared RBK

Motor Only Driver Only

1.8°/0.9°

PKP/PK

Geared PKP/PK

0.72°/0.36° PKP/PK

Accessories

Unipolar Driver for 1.8°/0.9° Stepper Motor



			Overview,
1	Driver Type		Product Series
2	2: 1.8°/0.9° Stepper Motor		ocnes
3	Power Supply Input Voltage	1:24 VDC	AC Input
4	Rated Current		Motor &
5	Signal I/O Mode	P: Photocoupler	Driver
			0.36°/Geared

Product Line

Product Name	List Price
CMD2109P	€111.00
CMD2112P	€111.00
CMD2120P	€111.00

Included

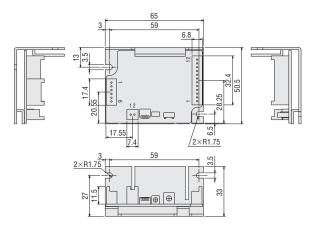
Туре	Connector for Driver Connection	Operating Manual
Common to All Types	For CN1 (1 Piece) For CN2 (1 Piece) For CN3 (1 Piece)	1 set

Specifications

Pro	oduct Name	CMD2109P	CMD2112P	CMD2120P
Drive Method		Microstep Drive, Unipolar constant-current drive method		
Motor Drive Current (Factory setting)		0.95 A/Phase	1.2 A/Phase	2 A/Phase
Power Supply	Voltage	24 VDC±10%		
Input Current A		1.5 1.7 2.9		2.9
Max. Input Pulse Frequency		100 kHz (When the pulse duty is 50%) Negative Logic Pulse Input		
Operating	Ambient Temperature	$0 \sim +40^{\circ}$ C (Non-freezing)		
Environment	Ambient Humidity	85% or Less (Non-condensing)		
(In operation)	Atmosphere	No corrosive gases or dust. The product should not be exposed to water, oil or other lic		

Dimensions (Unit = mm)

Product Name	Mass kg
CMD2109P	
CMD2112P	0.05
CMD2120P	
Included	
Connector Housing: 51103-0	200 (Molex)
51103-1	200 (Molex)
51103-0	600 (Molex)
Contact: 50351-8	3100 (Molex)



List of Applicable Motors

Driver Product Name	Motor Drive Current (Factory Setting)	Applicable Motor
CMD2109P	0.95 A/Phase	PKP213U, PKP214U, PKP22 U, PKP243U09 2, PKP243MU
CMD2112P	1.2 A/Phase	PKP23_U, PKP24_U12_2, PKP244MU
CMD2120P	2 A/Phase	PK25 [_] , PKP26 [_] U10 [_] 2, PKP26 [_] U20 [_] 2, PKP26 [_] MU

A number indicating the length of the motor case is entered where the box 🗌 is located within the names of the applicable motors.

Either A (single shaft) or B (double shaft) indicating the configuration is specified where the box is located in the names of the applicable motors.
 The applicable motors are listed such that the available combinations with the driver are distinguishable.

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 Combination with the appendix time and accord time are also quality.

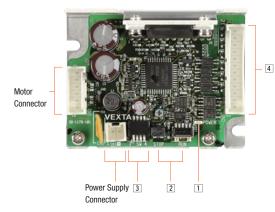
Combination with the encoder type and geared type are also available.

For details on the product name, please see the Oriental Motor website.



Connection and Operation (Unipolar Driver for 1.8°/0.9° Stepper Motor)

Names and Functions of Driver Parts



1 Power Supply Input Indicator

Color	Function	Lighting Condition	
Green Power Supply Indication		When power is applied	

2 Current Adjustment Switch

	•	
Indication	Switch Name	Function
RUN	Motor Running Current Adjustment Switch	The motor running current can be adjusted.
STOP	Motor Standstill Current Adjustment Potentiometer	The motor's standstill current can be adjusted.

3 Function Switch

Indication	Switch Name	Function
1 Pulse Input Mode Select Switch		The pulse input mode can be switched to 1-pulse input mode or 2-pulse input mode.
2, 3, 4 Step Angle Setting Switch		The switches can set any of 5 step angles.

Step Angle Setting Switch

SW-2	SW-3	SW-4	Resolution	Resolution	Step Angle
0FF	0FF	0FF	1	200	1.8°
0FF	0FF	ON	2	400	0.9°
0FF	ON	0FF	4	800	0.45°
0FF	ON	ON	8	1600	0.225°
ON	0FF	0FF	16	3200	0.1125°

Note

• The step angle is calculated by dividing the basic step angle by the resolution number. The values above figures are based on a basic step angle of 1.8°.

 With the high-resolution type, the basic step angle is 0.9°, and the resolution is 400 at resolution 1.

• With geared types, the step angle/gear ratio is the actual step angle.

 The step angle set with the step angle setting switches is effective when the step angle select (CS) input signal is OFF.

Do not change the step angle select input signal or step angle setting switches while the motor is running. The motor may misstep and stop. Change the step angle setting switches when the step angle select input signal is OFF and the excitation timing output signal is ON.

4 I/O Signal

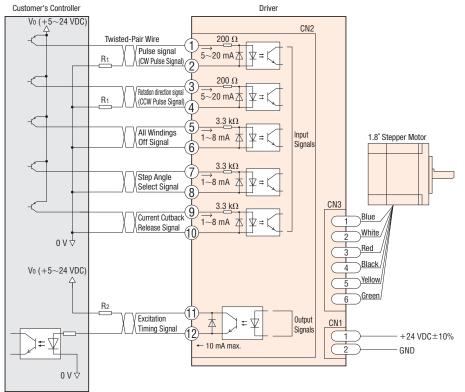
Indication	I/0	Pin No.	Signal Name	Function		
	Input Signals			1	Pulse Signal (CW Pulse	Operation command pulse signal (Rotates the motor in the CW direction
		2	Signal)	when in 2-pulse input mode.)		
			3	Rotation Direction Signal	Rotation direction signal Photocoupler "OFF": CCW and photocoupler "ON": CW	
		4	(CCW Pulse Signal)	(Rotates the motor in the CCW direction when in 2-pulse input mode.)		
		5	All Windings Off Signal	All windings of the motor are set to OFF and the motor shaft can be rotated by external force.		
CN2		6				
		S	Step Angle Select Input	The motor operates at the basic step angle regardless of how the step angle		
			8	Signal	setting switches are set.	
		9	Automatic Current Cutback	This signal is used to disable the		
		10	Release Signal	automatic current cutback function.		
	Output Signals	11	Excitation	This signal is output when the excitation		
		12	Timing Signal	sequence is step "0".		

[•] If a combination not listed in the table is set, the resolution becomes 1, and the motor operates at the basic step angle.

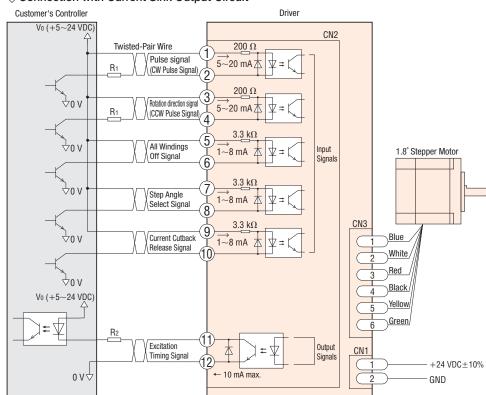
Stepper Motors A-447

Connection Diagram

♦ Connection with Current Source Output Circuit



♦ Connection with Current Sink Output Circuit



[Notes on Wiring]

I/O Signal Connection Input signal

- The external resistor is not needed when 5 VDC is applied. If voltage exceeding 5 VDC is applied, connect an external resistor R₁ so that the current becomes 5~20 mA.
- Example) When V₀ is 24 VDC, R₁: 1.5~2.2 kΩ 0.5 W min.
 Output signal Check the specifications of the connected devices, and if
- the current exceeds 10 mA, connect the external resistor R2.
- Use twisted-pair cables of AWG24~22 (0.2~0.3 mm²).
 Note that as the length of the pulse line increases, the max.
- transmission frequency decreases, and keep the wiring length as short as possible (2 m max.). Provide a distance of 100 mm min. between the signal lines
- and power lines (such as power supply lines and motor lines).

◇Power Supply Connection

- Use a wire of AWG22 (0.3 mm²).
 Incorrect polarities of the DC power-supply input will damage the driver. Make sure that the polarity is correct before turning the power on.

• Use a wire of AWG22 (0.3 mm²) min.

⇔General

- A separate hand crimp tool is required to crimp the connector and lead wires included with the driver.
 Connection cable sets which are available as accessories (sold separately) have already had their lead wires crimped.
- If a specific wiring and layout causes the motor cable or power supply cable to generate a noise problem, shield the cable or use ferrite cores.

Overview, Product Series

AC Input Motor & Driver

> 0.36°/Geared *Xstep* Absolute **AZ**

0.36°/Geared

0.72°/Geared RKII

DC Input Motor & Driver

0.36°/Geared *Xstep* Absolute **AZ**

0.36°/Geared

1.8°/0.72

/0.36° CVK 0.72°/0.36° /Geared

CRK 1.8°/Geared

Motor Only Driver Only

RBK

1.8°/0.9° **PKP/PK**

Geared PKP/PK

0.72°/0.36° **PKP/PK**

Driver

Accessories